



# e-LOOP Diagnostics Remote Reference

This document acts as a quick reference guide for the diagnostic's remote settings for the e-loop. It briefly describes what each menu item represents. For further detail, the diagnostics remote manual should be referenced.



# **Loop Settings**

## Op Mode

e-loop operation mode (Exit, Presence, Parking).

# Trip Value.

 Magnetometer measurement value that measurement must be greater than for a magnetometer detection.

### X Axis

 Percentage that the x-axis (left to right) is used for a magnetometer measurement.

### Y Axis

 Percentage that the y-axis (front to back) is used for a magnetometer measurement.

### Z Axis

 Percentage that the z-axis (up and down) is used for a magnetometer measurement.

### **Mag Speed**

- Whether the magnetometer uses an average of the last 10 measurements or a single measurement when determining a nonmagnetometer detection.
- Using the average results in a slower detection release.

# **Low Battery**

 The voltage trip level used to determine that the battery is getting low.

# **Diagnostics**

# The current e-loop state is shown on the diagnostics menu entry.

- Current detection status (whether a vehicle is detected or not).
- Radar mode status (Whether the system is currently in radar-only mode).

### Reading

The latest magnetometer measurement value.

# **Trip Value**

The magnetometer measurement level for detection.

### Temperature

The current temperature of the magnetometer in °C.

### Ban

 How many e-loop readings the auto compensation is turned off for?

### Reset

· Last known reset cause.

# RSSI

 The radio signal strength between the diagnostics remote and the connected e-loop in dBm.

### Calibrate

Calibrate or uncalibrate the e-loop without using the Magnet.



# **Device Test**

# The device test checks the sensors and peripherals to make sure that they are working correctly.

 Refer to the test mode reference card for more information on errors during this test.

## **RSSI Check**

 Initiates a radio connection check between the e-loop and it's paired receiver.

# **Radar settings**

# **Release Trip**

 The magnetometer measurement level that magnetometer measurement must be below to unlatch the e-loop.

### Start Len

 The distance in meters that the radar will start measuring from, anything before this distance is considered a detection dead zone.

## Measure Len

• The distance in meters that the radar will measure from the radar start length.

# **Radar Trip**

 Radar measurement level that a radar measurement must cross for a detection to occur.

# **Radar Confirm**

 Sets whether the system requires the radar to confirm the magnetometer detection when a vehicle is being detected by the eloop.

### Radar Int

 How often in seconds the radar checks the detection of a vehicle is correct.

# **Advanced Radar**

### **Wait Time**

 How often the system checks the radar when in radar only mode.

### **Park Wait Time**

 How long the system waits between a magnetometer detection, and confirming the detection with the radar when the e-loop is set to parking mode.

# Radar Read

# Reads the radar and reports whether the radar is detecting or not detecting.

Radar read true reports that a vehicle is detected.

Radar read false reports that no vehicle is detected.

# **Device info**

### Software build date

Date the software that is used in the connected e-loop was built.

# Software version

The version number of the software in the connected e-loop.